SUMMARY OF APPEAL PROPOSAL DRAWINGS & IMAGES

CONTEXT: DRAWINGS: PRECEDENTS

Former Buzz Bingo | Banbury | Oxfordshire | OX160TH

JULY 2022





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Maps

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1.1 LOCATION OF SITE - UNITED KINGDOM

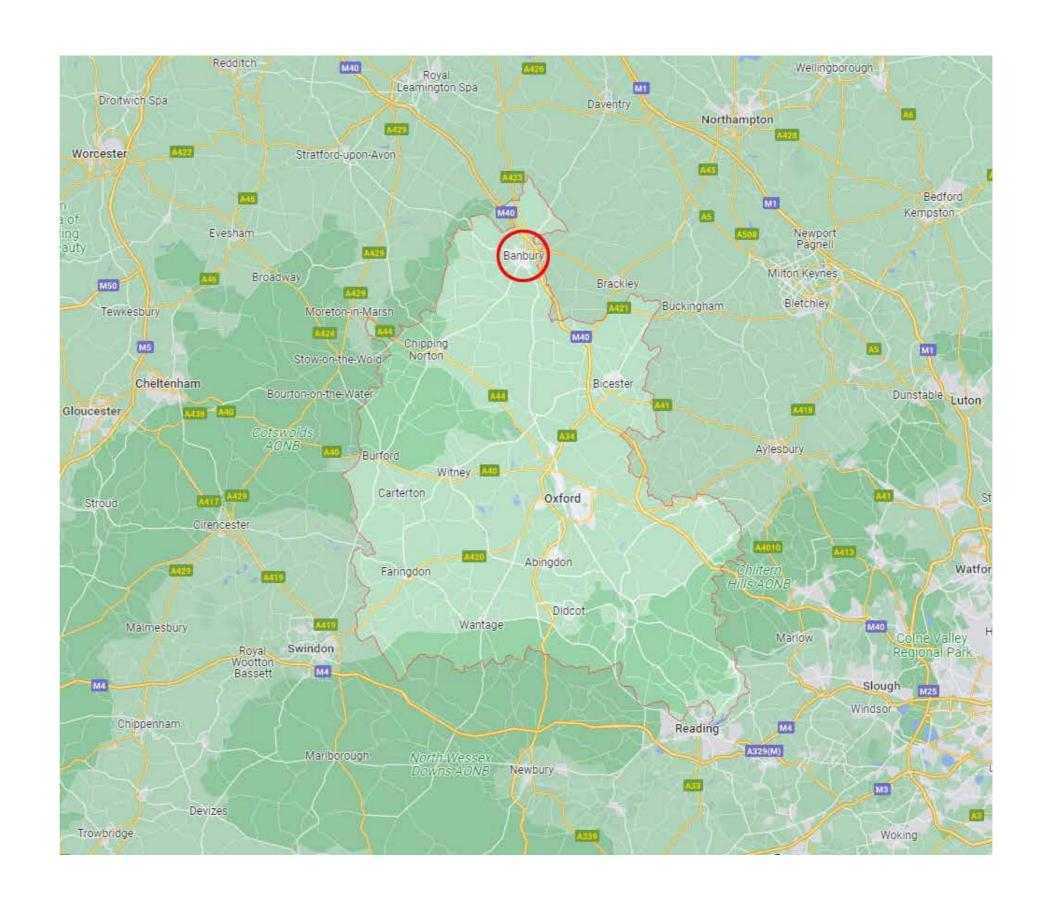
Location of Oxfordshire within the United Kingdom.





1.2 LOCATION OF SITE - OXFORDSHIRE

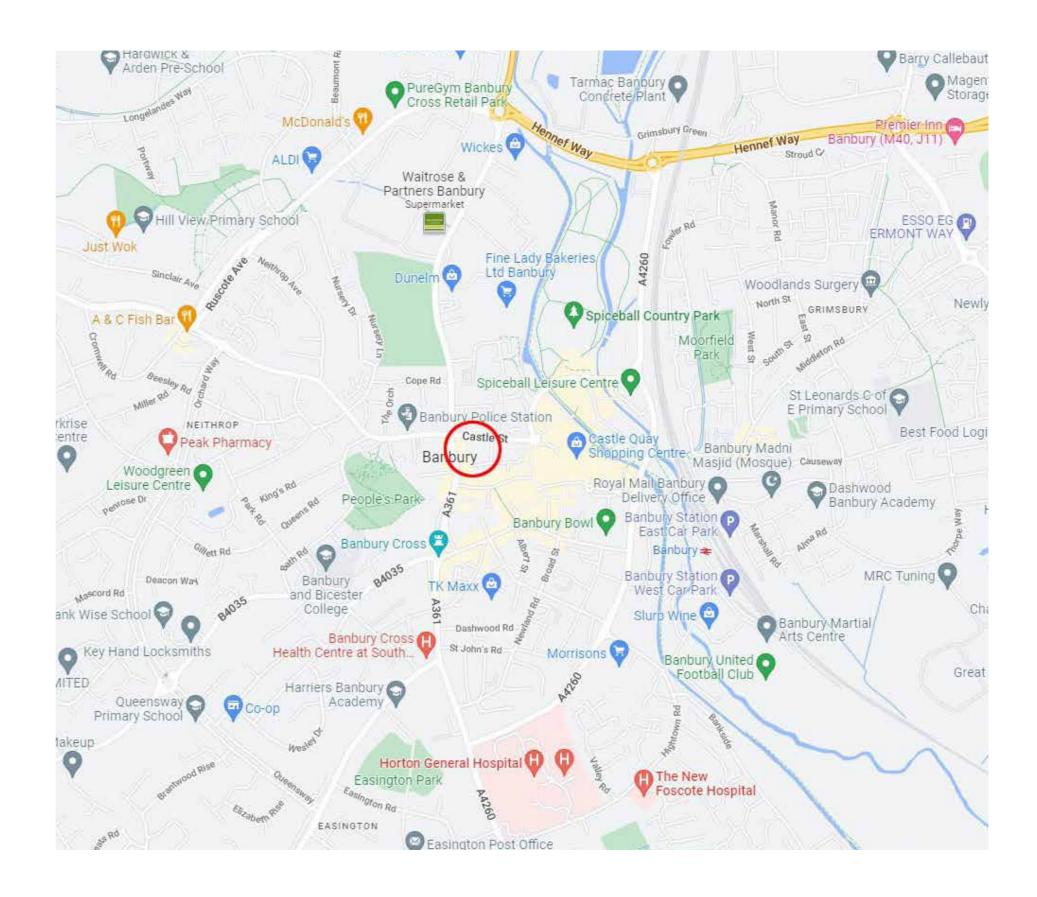
Location of Banbury within Oxfordshire.





1.3 LOCATION OF SITE - BANBURY

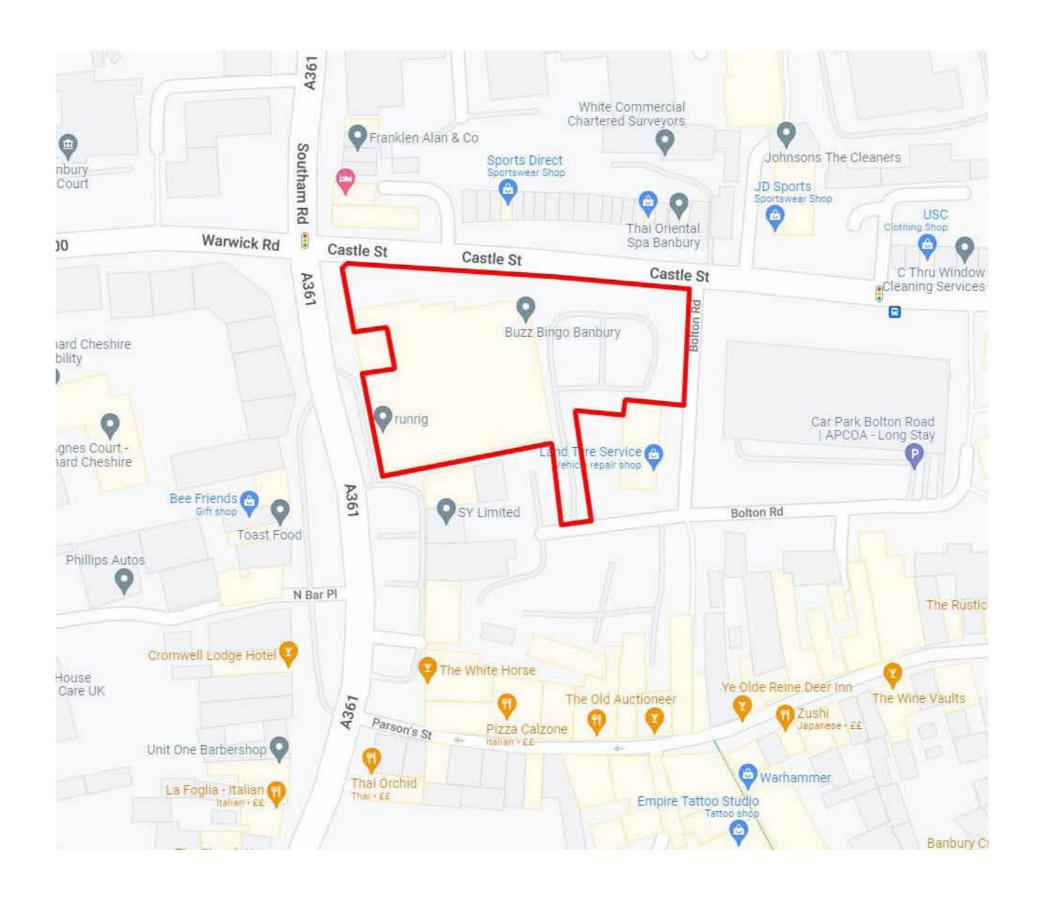
Location of the Site within Banbury.





1.4 LOCATION OF SITE - CASTLE STREET

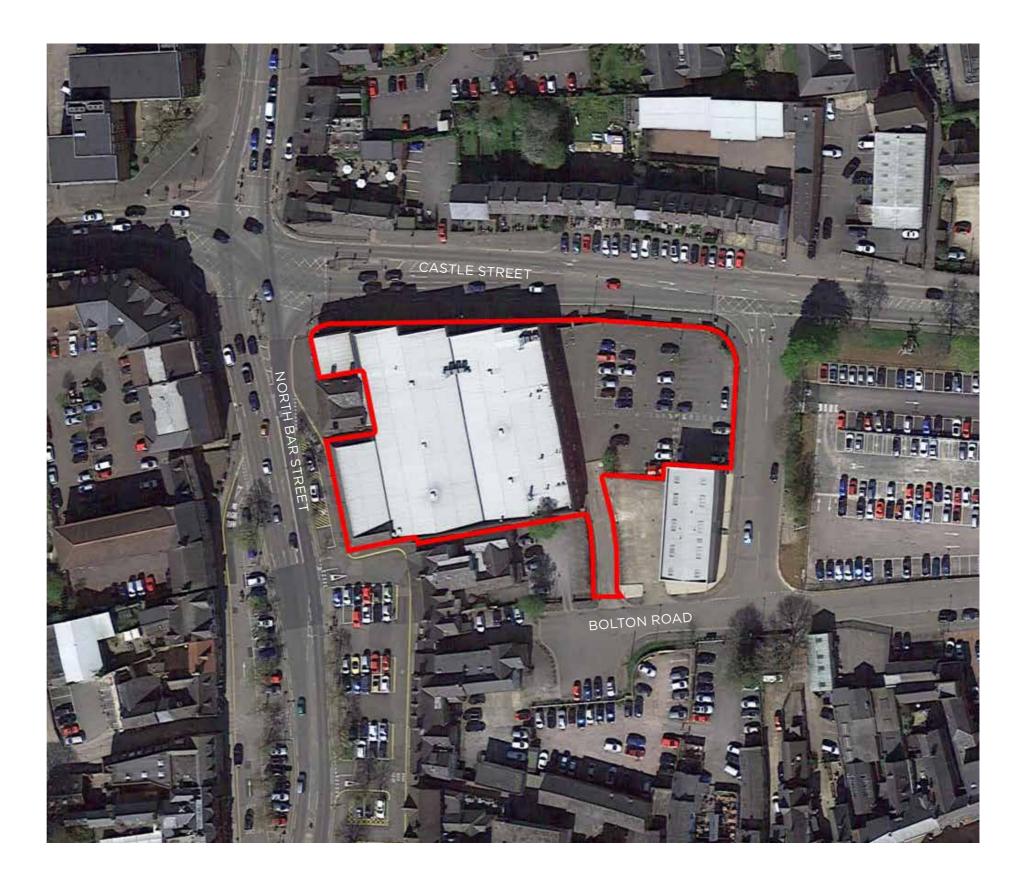
Location of the Site in relation to Castle Street, North Bar Street and Bolton Road.





1.5 LOCATION OF SITE - AERIAL IMAGE

Aerial Image of the Site in relation to Castle Street, North Bar Street and Bolton Road.





1.6 LOCATION OF SITE - LOCAL POLICY

Location of the Site in relation to Banbury Vision Document SPD site 'Banbury 8'.

Bolton Road development area (Banbury 8)

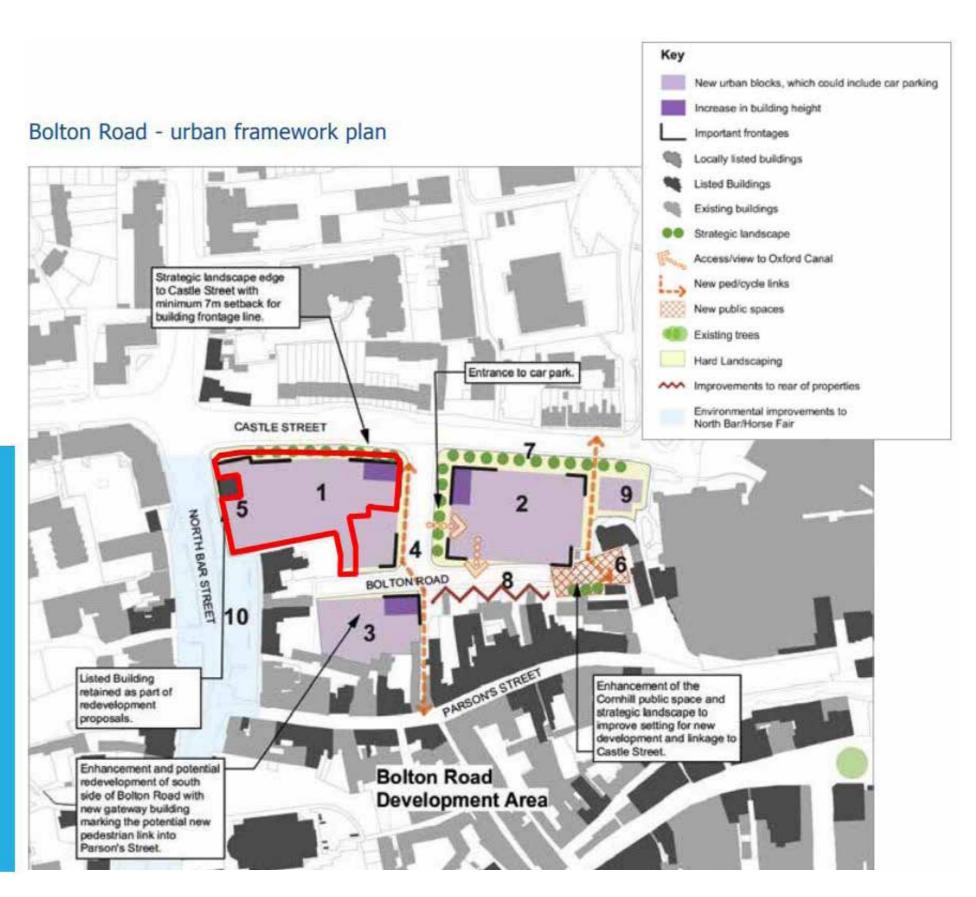
Development proposals should be consistent with the design principles below, which build on the Local Plan Policy.

Key urban design/development principles

- three development areas (1, 2 and 3) by the development for residential and town centre uses. Existing modern buildings will need to be removed if Area 1 comes forward for remain on the site.
- car parking and perimeter mixed use along
- Area 3 includes the surface car park behind Parson's Street to be developed for mixed use with a gateway building forming a frontage and access to Parson's Street through a new pedestrian link. The special historic architectural character of the listed buildings and their settings to be considered
- as part of any redevelopment proposals. New pedestrian and cycle link through the the Bolton Road Development and car park to retail activity on Parson's Street.
- Existing Listed Buildings fronting onto Parson's Street and North Bar Street to development area should seek to preserve and enhance listed buildings and the

The Urban Framework Plan opposite illustrates a development solution following the urban design principles:

- the eastern end of Bolton Road and a new pedestrian/cycle link onto Castle Street to improve town centre accessibility.
- Improved frontage onto Castle Street with strategic landscaping.
 Bolton Road retained for service access to
- rear of Parson's Street properties. Consideration to be given to the inclusion of the rear of Parson's Street as part of the development area after consultation with
- redeveloped.
 Environmental improvements to North Bar realm, landscape and car parking improvements.





1.7 LOCATION OF SITE - URBAN GRAIN

Figure Ground diagram as existing

Figure Ground diagram as proposed





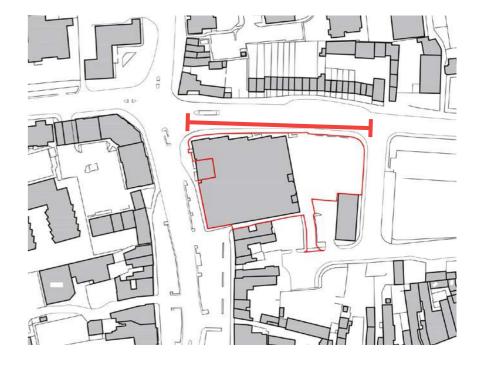
2 Context Photos

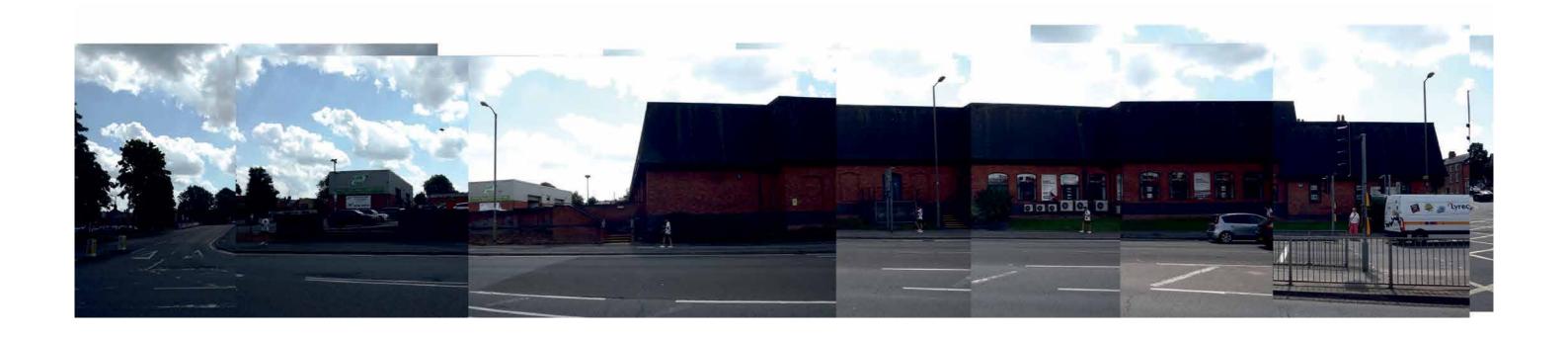
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2.22	Context - Bolton Road	33



2.1 CONTEXT - CASTLE STREET

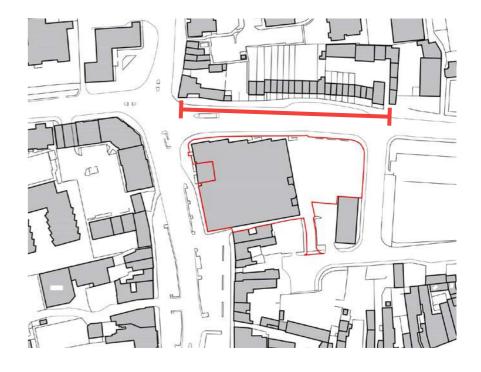
Southern side of Castle Street, looking at Site.





2.2 CONTEXT - CASTLE STREET

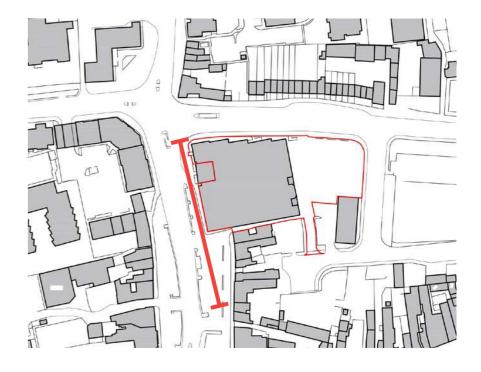
Northern side of Castle Street, opposite proposed Site.





2.3 CONTEXT - NORTH BAR STREET

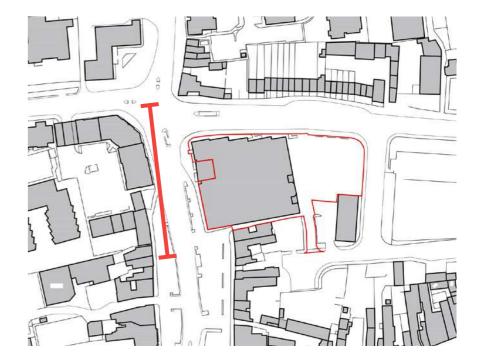
Eastern side of North Bar Street, looking at Site.





2.4 CONTEXT - NORTH BAR STREET

Western side of North Bar Street, opposite proposed Site.







2.5 CONTEXT - NORTH BAR STREET

View of North Bar Street, looking north.



2.6 CONTEXT - NORTH BAR STREET

View of North Bar Street, looking south.





2.7 CONTEXT - NORTH BAR STREET

View of North Bar Street, looking north.



2.8 CONTEXT - NORTH BAR STREET

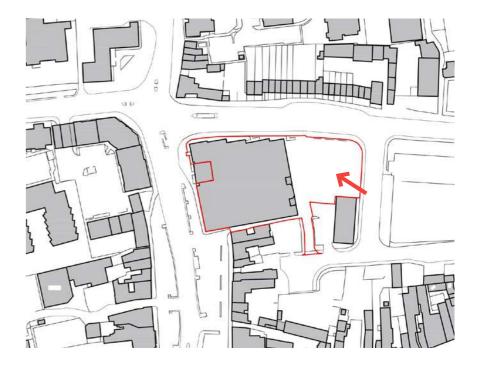
View of North Bar Street, looking south.





2.9 CONTEXT - BINGO HALL CAR PARK

View of Bingo Hall car park, looking north-west.

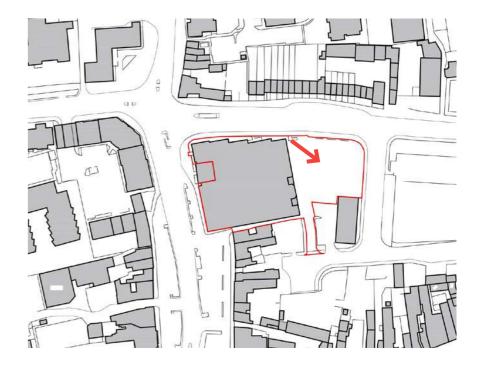






2.10 CONTEXT - BINGO HALL CAR PARK

View of Bingo Hall car park, looking south-east.

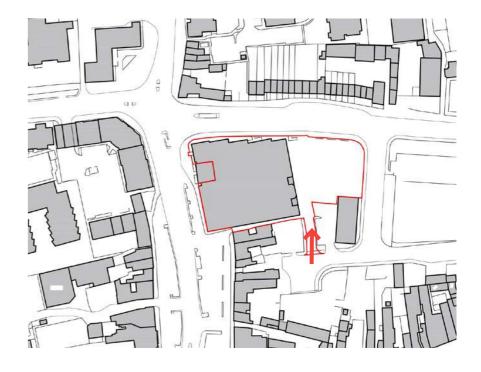






2.11 CONTEXT - ACCESS FROM BOLTON ROAD

View of access road, looking north.







2.12 CONTEXT - CASTLE STREET

View of Castle Street, looking west.





2.13 CONTEXT - CASTLE STREET

View of Castle Street, looking west.



2.14 CONTEXT - SOUTHAM ROAD

View of Southam Road, looking south.





2.15 CONTEXT - WARWICK ROAD

View of corner of Southam Road and Warwick Road, looking north.





2.16 CONTEXT - WARWICK ROAD

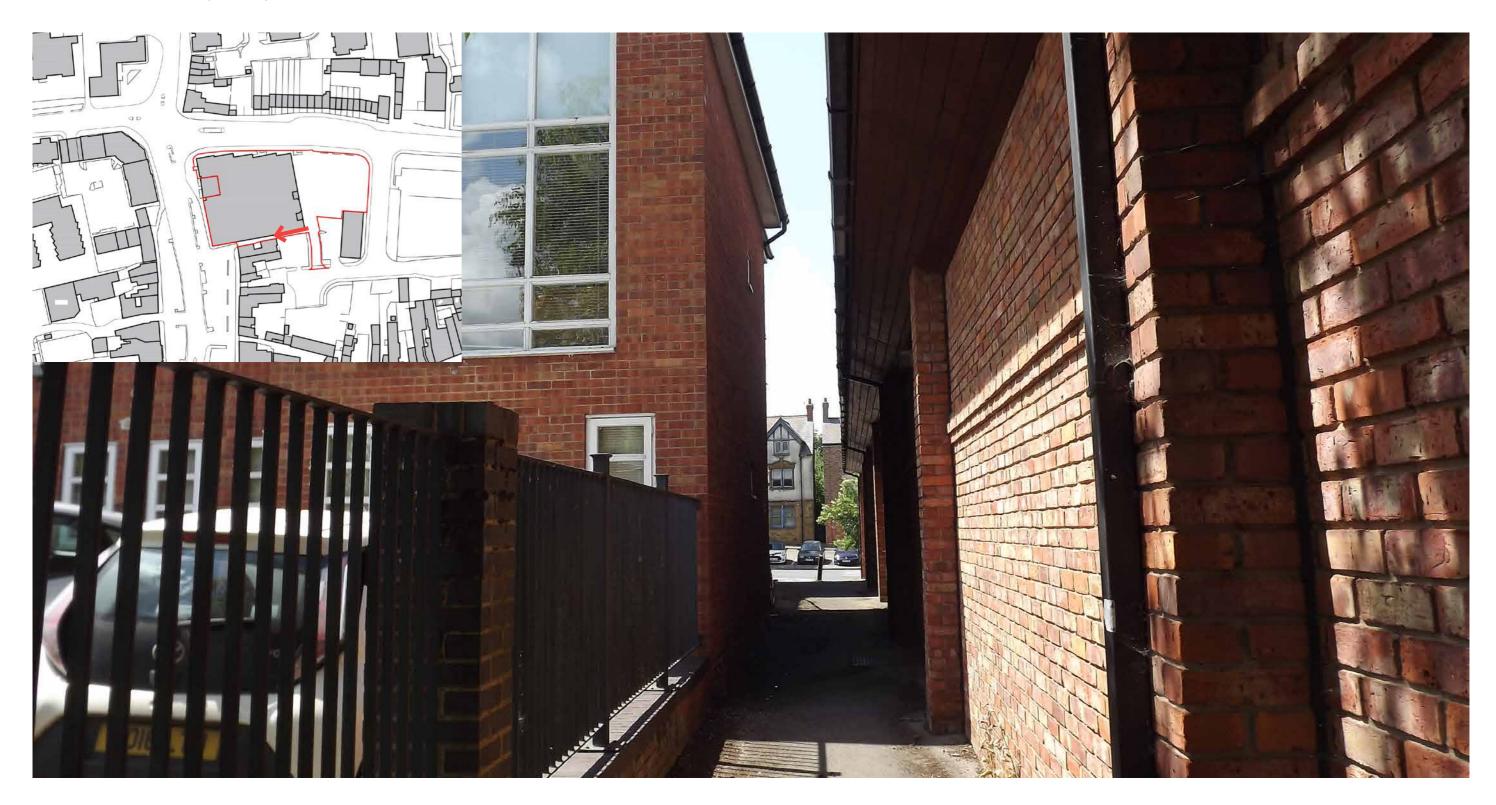
View of Warwick Road, looking east.





2.17 CONTEXT - SOUTHERN BOUNDARY

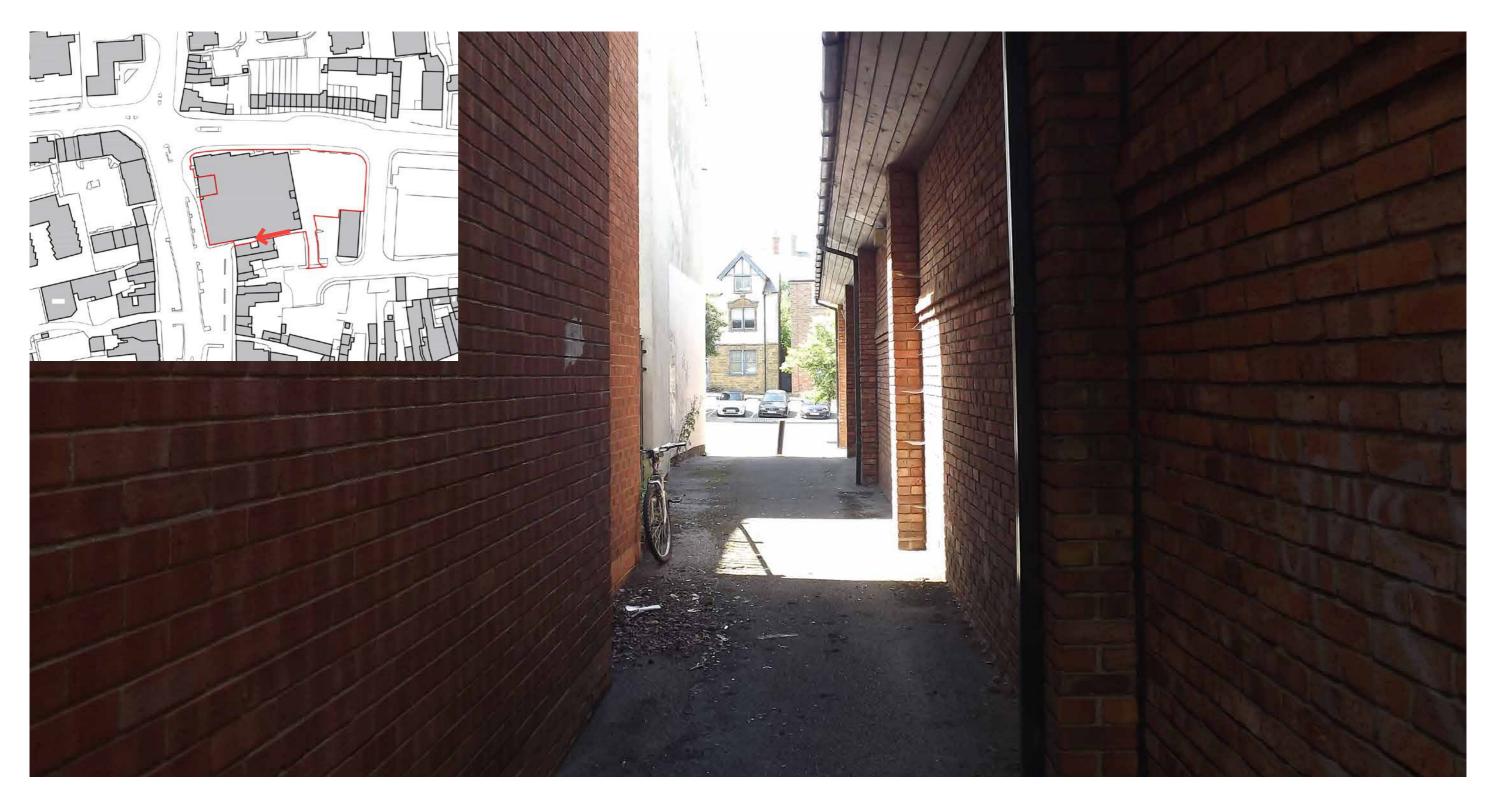
View of southern boundary, looking west.





2.18 CONTEXT - SOUTHERN BOUNDARY

View of southern boundary, looking west.





2.19 CONTEXT - SOUTHERN BOUNDARY

View of southern boundary, looking west.





2.20 CONTEXT - SOUTHERN BOUNDARY

View of southern boundary, looking north-east.



2.21 CONTEXT - BOLTON ROAD

View of Bolton Road, looking south





2.22 CONTEXT - BOLTON ROAD

View of Bolton Road, looking west





3 PRECEDENT CHURCHILL DEVELOPMENTS

Precedent Churchill Developments

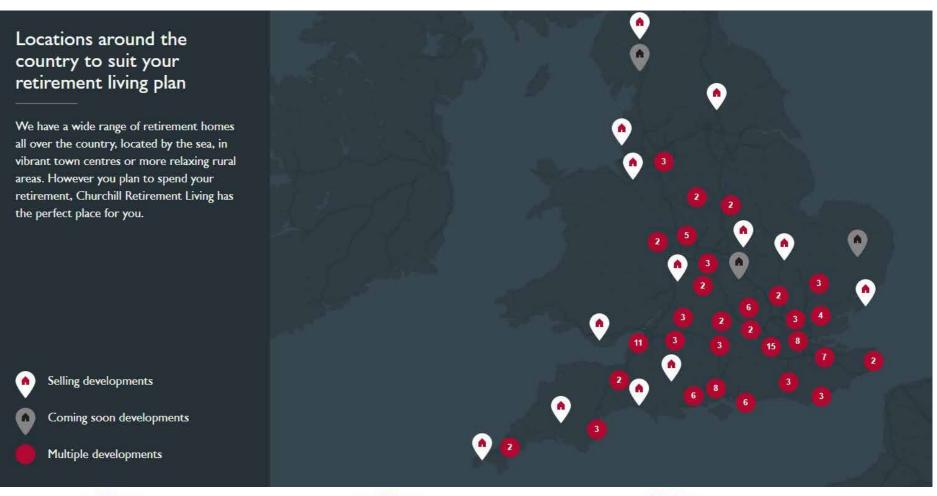
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3.14	St Athelm Lodge. Wells	48



PRECEDENT CHURCHILL DEVELOPMENTS

3.1 LOCATIONS AND AWARDS

Churchill Retirement Living has designed and constructed a large variety of retirement living developments across the country, and received multiple awards.





2020









BEST REGENERATION SCHEME





HOUSEBUILDER OF THE YEAR

BEST MEDIUM HOUSEBUILDER

BEST MEDIUM HOUSEBUILDER

BEST RETIREMENT DEVELOPMENT



3 PRECEDENT CHURCHILL DEVELOPMENTS

3.2 RECENT RETIREMENT DEVELOPMENT

Fitzford Lodge, Tavistock





3.3 RECENT RETIREMENT DEVELOPMENT

Sarum Lodge, Salisbury





3 PRECEDENT CHURCHILL DEVELOPMENTS

3.4 RECENT RETIREMENT DEVELOPMENT

Priory Lodge, Christchurch





3 PRECEDENT CHURCHILL DEVELOPMENTS

3.5 RECENT RETIREMENT DEVELOPMENT

Arlington Lodge, Leamington Spa





3.6 RECENT RETIREMENT DEVELOPMENT

Lewis Carroll Lodge, Cheltenham





3 PRECEDENT CHURCHILL DEVELOPMENTS

3.7 RECENT RETIREMENT DEVELOPMENT

Alfred Lodge, Bridport





3.8 RECENT RETIREMENT DEVELOPMENT

Albert Lodge, Abingdon





3.9 RECENT RETIREMENT DEVELOPMENT

St. Andrew's Lodge, Chippenham





3 PRECEDENT CHURCHILL DEVELOPMENTS

3.10 RECENT RETIREMENT DEVELOPMENT

Hardy Lodge, Shaftesbury





3.11 RECENT RETIREMENT DEVELOPMENT

Hubert Lodge, Hythe





3.12 RECENT RETIREMENT DEVELOPMENT

William Lodge, Malmesbury





3.13 RECENT RETIREMENT DEVELOPMENT

King Edgar Lodge, Ringwood





3.14 RECENT RETIREMENT DEVELOPMENT

St. Athelm Lodge, Wells





4 Appeal Plans and Elevations

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4.1 SITE PLAN

PA01 Site Plan





4.2 GROUND FLOOR PLAN PA02 Ground Floor Plan Trelawn House Ground Floor Plan Churchill
Retirement Living



10116BB - PA02

4.3 FIRST FLOOR PLAN

PA03 First Floor Plan



4.4 SECOND FLOOR PLAN

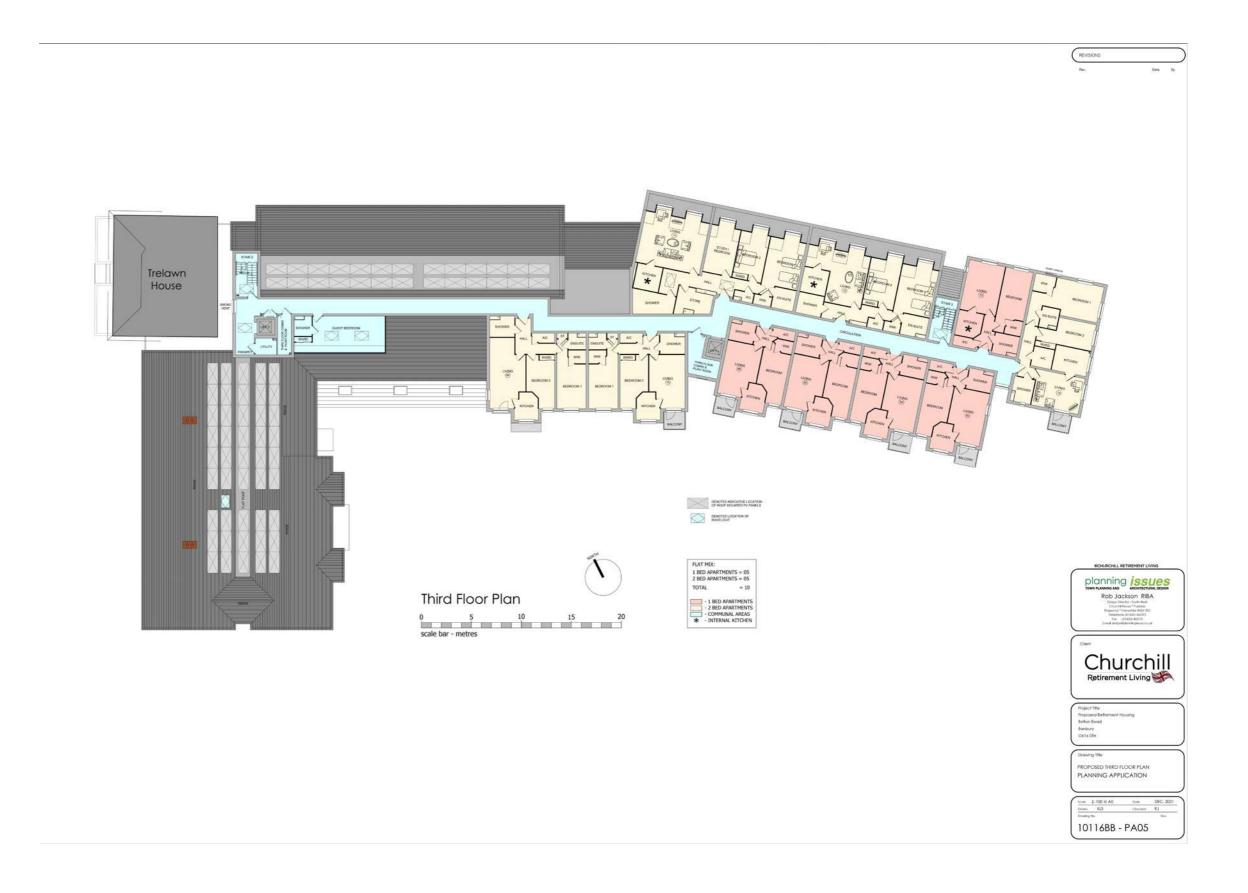
PA04 Second Floor Plan





4.5 THIRD FLOOR PLAN

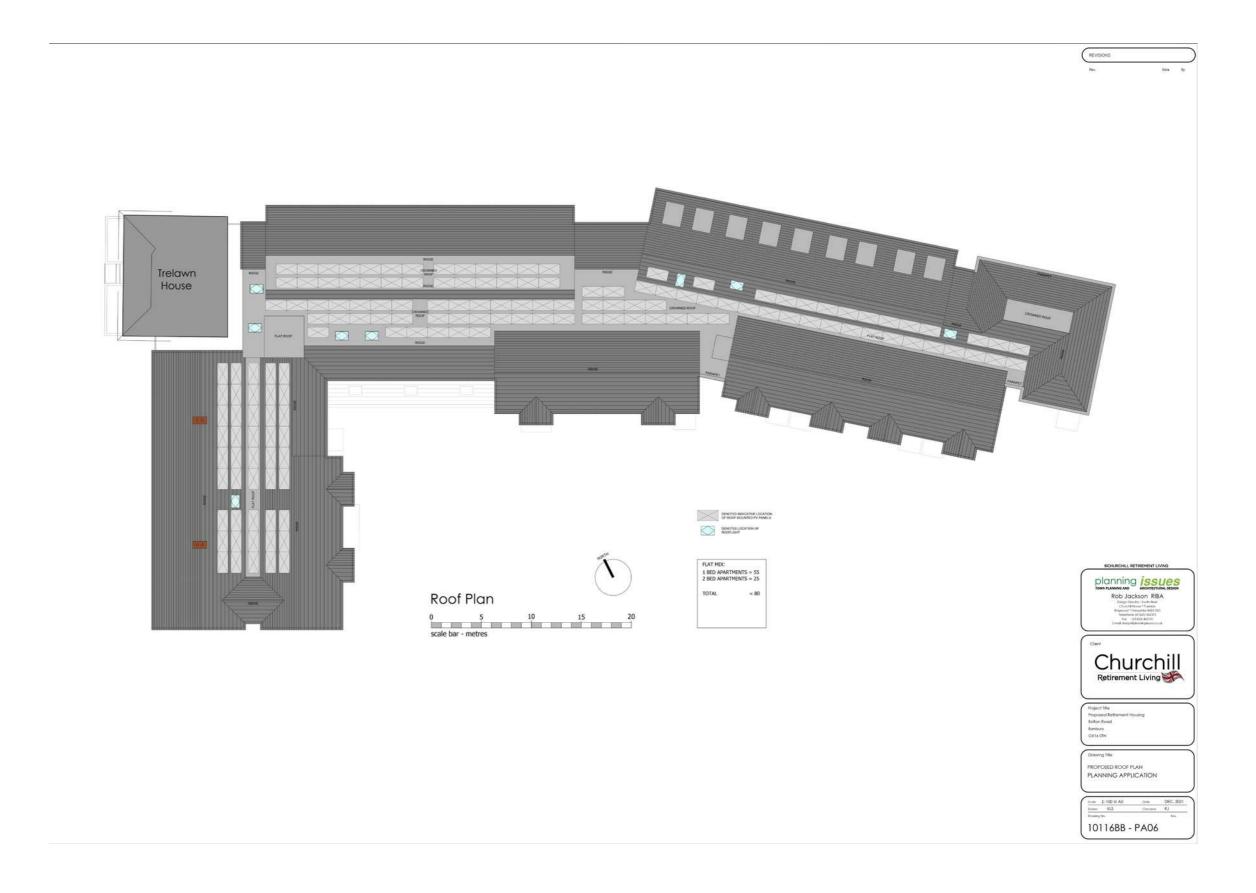
PA05 Third Floor Plan





4.6 ROOF PLAN

PA06 Roof Plan





4.7 CASTLE STREET ELEVATION

PA07 Castle Street Elevation

Please note that the drawing was listed as PAO7 for the planning application, but incorrectly numbered as RFO7.





4.8 NORTH BAR STREET ELEVATION

PA08 North Bar Street Elevation

Please note that the drawing was listed as PAO8 for the planning application, but incorrectly numbered as RFO8.





4.9 INTERNAL AND OTHER ELEVATIONS

PA09 Other Elevations

Please note that the drawing was listed as PA09 for the planning application, but incorrectly numbered as RF09.





4.10 SITE SECTIONS

PA10 Site Sections



4.11 SITE PLAN (TRELAWN HOUSE)

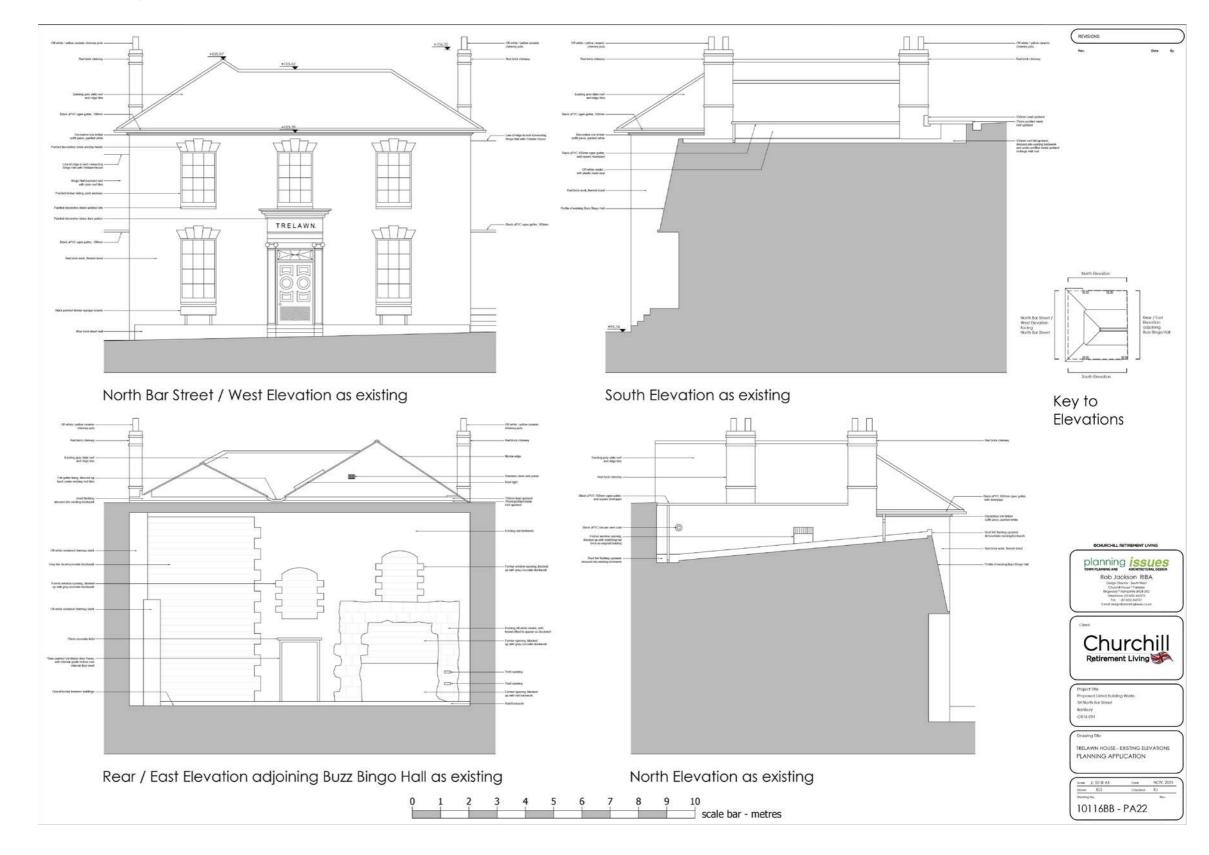
PA21 Site Plan





4.12 EXISTING ELEVATIONS (TRELAWN HOUSE)

PA22 Existing Elevations



4.13 WORKS AS PROPOSED (TRELAWN HOUSE)

PA23 Works as Proposed





5 Verified Views (Winter)

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5.1 VERIFIED VIEWS - VIEW LOCATIONS

List of Figures

Fig. 01: View 1 - Castle Street Existing

Fig. 02: View 1 - Castle Street Proposed

Fig. 03: View 1 - Castle Street - Data Sheet

Fig. 04: View 2 - Bolton Road Existing

Fig. 05: View 2 - Bolton Road Proposed

Fig. 06: View 2 - Bolton Road - Data Sheet

Fig. 07: View 2 - N Bar Street Existing Baseline

Fig. 08: View 2 - N Bar Street Proposed

Fig. 09: View 2 - N Bar Street - Data Sheet

Fig. 10: View 3 - Warwick Road Existing

Fig. 11: View 3 - Warwick Road Proposed

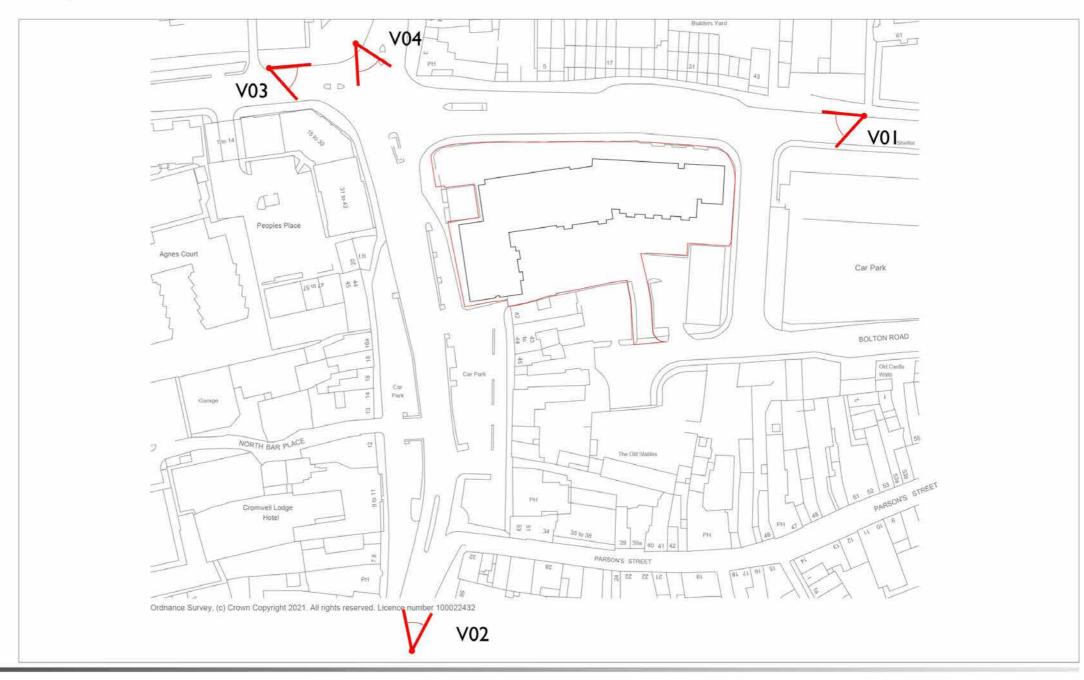
Fig. 12: View 3 - Warwick Road - Data Sheet

Fig. 13: View 4 - Southam Road Existing

Fig. 14: View 4 - Southam Road Proposed

Fig. 15: View 4 - Southam Road - Data Sheet

Viewpoint Location Plan







5.2 VERIFIED VIEWS - CASTLE STREET AS EXISTING





Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 01: View 1 - Castle Street Existing	

5.3 VERIFIED VIEWS - CASTLE STREET AS PROPOSED





Ocm (Original image width 523mm) 10cm

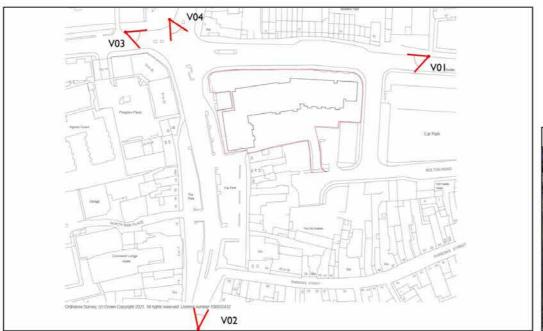
Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 02: View 1 - Castle Street Proposed	

5.4 VERIFIED VIEWS - CASTLE STREET VIEW METHODOLOGY



Survey Reference Points



Information:

- If viewing this view on a screen, enlarge to full screen height. A scale bar is provided to calibrate correct sizing.
- Images should be viewed at comfortable arm's length.
- Coordinates of all survey reference points indicated on the image to the left can be supplied upon request

View N

Visualisation Type

AVR Level 3

Location Castle Stre

Coordinates 445527, 240774 (to EPSG 27700)

Bearing of View 249 V

Sistance to centre Site 53m

View Level (AOD) 96.53 AOI

VIEW LEVEL (NOD) 30.33 NOD,

Camera Height 1.6m above ground levels

amera Canon EOS 5D MK II

Frame Type Composi

Projection Planar

Jigina 30

Vertical FOV 27

Date of Photo 10/12/2021 10:56

Weather Sun





View Location

View Verification

View Verification



Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 03: View 1 - Castle Street - Data Sheet	



5.5 VERIFIED VIEWS - NORTH BAR STREET AS EXISTING





5.6 VERIFIED VIEWS - NORTH BAR STREET AS PROPOSED

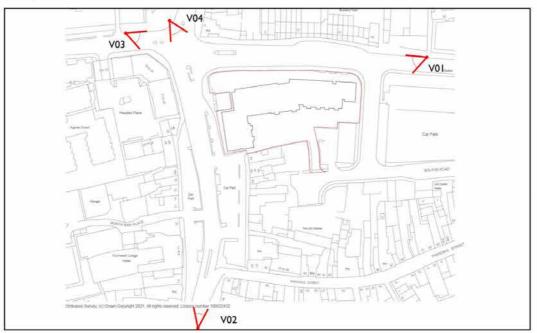




5.7 VERIFIED VIEWS - NORTH BAR STREET VIEW METHODOLOGY



Survey Reference Points



Information:

- If viewing this view on a screen, enlarge to full screen height. A scale bar is provided to calibrate correct sizing.
- Images should be viewed at comfortable arm's length.
- Coordinates of all survey reference points indicated on the image to the left can be supplied upon request

View Number 3
Visualisation Type Ty

Location N Bar Stre

Coordinates 445366, 240585 (to EPSG 27700)

Bearing of View 8 N

Distance to centre Site 122

View Level (AOD) 103.11 AOD

Camera Height 1.6m above ground levels

Camera Canon EOS 5D MK III

Frame Type Composite

Projection Planar

ens Focal Length Sigma 50mm

Vertical FOV 27

Date of Photo 10/12/2021 11:29

Weather Sur





View Location

View Verification

View Verification



Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 06: View 2 - N Bar Street - Data Sheet	



5.8 VERIFIED VIEWS - WARWICK ROAD AS EXISTING



NPA Visuals
Nicholas Pearson Associates

Ocm (Original image width 523mm)	10cm
----------------------------------	------

Project No:	11208-009	Date:	March 2022
Client:	Churchill Retirement	Project:	Bolton Road, Banbury
Status:	Planning	Figure:	Fig. 07: View 3 - Warwick Road Existing

5.9 VERIFIED VIEWS - WARWICK ROAD AS PROPOSED



NPA Visuals
Nicholas Pearson Associates

Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

 Project No:
 11208-009
 Date:
 March 2022.

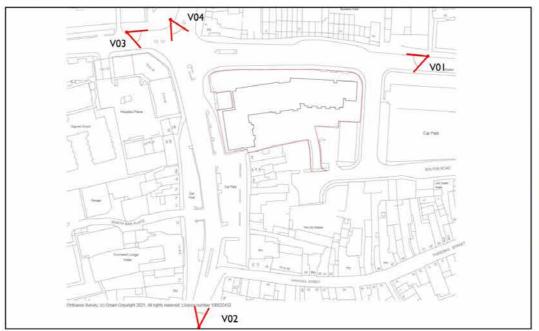
 Client:
 Churchill Retirement
 Project:
 Bolton Road, Banbury

 Status:
 Planning
 Figure:
 Fig. 08: View 3 - Warwick Road Proposed

5.10 VERIFIED VIEWS - WARWICK ROAD VIEW METHODOLOGY



Survey Reference Points



Information:

- If viewing this view on a screen, enlarge to full screen height. A scale bar is provided to calibrate correct sizing.
- Images should be viewed at comfortable arm's length.
- Coordinates of all survey reference points indicated on the image to the left can be supplied upon request

View Number 4
Visualisation Type Typ

Location Warwick Roa

Coordinates 445316, 240791 (to EPSG 27700)

Bearing of View 112

istance to centre Site 67n

View Level (AOD) 97 30 AC

Camera Height 1.6m above ground levels

Camera Canon EOS 5D MK III

rame Type Composite

Projection Planar

ens Focal Length Sigma 50mn

onenminative via

Date of Photo 10/12/2021 12:55

Weather Sur





View Location

View Verification

View Verification

NPA Visuals
Nicholas Pearson Associates

Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 09: View 3 - Warwick Road - Data Sheet	



5.11 VERIFIED VIEWS - CASTLE STREET / NORTH BAR STREET JUNCTION AS EXISTING





Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No:	11208-009	Date:	March 2022
Client:	Churchill Retirement	Project:	Bolton Road, Banbury
Status:	Planning	Figure:	Fig. 10: View 4 - Southam Road Existing

5.12 VERIFIED VIEWS - CASTLE STREET / NORTH BAR STREET JUNCTION AS PROPOSED





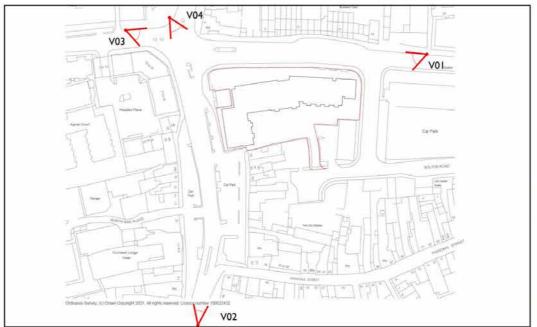
Ocm (Original image width 523mm) 10	0cm	(Original image width 523mm)	10cm
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Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 11: View 4 - Southam Road Proposed	

5.13 VERIFIED VIEWS - CASTLE STREET / NORTH BAR STREET JUNCTION VIEW METHODOLOGY



Survey Reference Points



Inforr

- If viewing this view on a screen, enlarge to full screen height. A scale bar is provided to calibrate correct sizing.
- Images should be viewed at comfortable arm's length.
- Coordinates of all survey reference points indicated on the image to the left can be supplied upon request

Information:

View Number 5

Visualisation Type Typ

Location

Coordinates 445347, 240800 (to EPSG 27700)

Bearing of View 150

2000 F 2000 2000 F 2000

amera Canon EOS 5D MK III

rame Type Composite

5.

SECTION SECTION

ertical FOV 27°

Date of Photo 10/12/2021 12:58

Weather Sur





View Verification View Verification



View Location

Project No:	11208-009	Date:	March 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 12: View 4 - Southam Road - Data Sheet	



5.14 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

Introduction

A Verified View is an image that combines a photographic view with an accurate 3d CAD representation of a proposed development, displayed to an agreed level of detail. Using a baseline of verifiable visual data and information, its purpose is to impartially and if required, realistically represent the proposal. Not just the appearance and context, but also its scale. By using verifiable visual data this image can then be used by others (if required) to scrutinise the work, without its accuracy being questioned.

"Photographs can have an important role to play in communicating information about the landscape and the visual effects of a proposed development, although they cannot convey exactly the way that the effects would appear on site." (GLVIA, Third Edition)

Verified Views are also referred to as:

Visually Verifiable Montages (VVM)

Verified Visual Image (VVI)

Accurate Visual Representation (AVR)

We have an established reputation for the production of Verified Views for both urban and rural developments and have successfully presented these for planning applications and as expert witnesses at public inquiry.

The methodology used by us accords with the following guidance documents where appropriate:

The Third Edition of the good practice 'Guidelines for Landscape and Visual Impact Assessment' 2013; produced by the Landscape Institute and Institute of Environmental Management & Assessment.

Visual Representation of Development Proposals, September 2019. Landscape Institute Technical Guidance Note 06/19

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'Visualisation Standards for Wind Energy Developments' (July 2016), The Highland Council

When producing verified views, a series of options are available to aid design and planning decisions according to the level of detail required. To assist agreement between all parties prior to (AVR) preparation, the following classification types are presented to broadly define the purpose of an AVR in terms of the visual properties it represents.

This classification is a cumulative scale in which each level incorporates all the properties of the previous level.

AVR Level 0 Location and size of proposal

AVR Level 1 As level 0 + degree of visibility of proposal

AVR Level 2 As level 1 + visual architectural form and details

AVR Level 3 As level 2 + use of realistic materials and lighting

Visulisations 'Types' according to the Landscape Institute guidance note 06/19 refer to the following

Type 4: visualisations where the highest level of locational accuracy. Image scaleing may be required.

Type 3: Visulialisations where a verifiable process and printed scale representation is not required

Appendix A includes a project specific methodology pro-forma detailing which principles from this methodology have been applied.

Preparation

Each view of the proposal is represented so that an informed decision can be made by balancing the needs of the assessor or viewer on site. Wherever possible, consultation with the relevant planning professional takes place on the matter and our final methodology is based on the most appropriate agreed set of professional Guidance

Initially all baseline and proposal data is compiled so we can plan and agree the viewpoint locations with the client and relevant authorities. If the information is available we will also "pre-visualise" the viewpoints showing both the existing and proposed. This can also be used as an accurate guide on site and discuss all options with the client to ensure that our site photography covers all the potential locations and captures the full extent of the proposed scene correctly.

Prior to the site visit we prepare a "site pack" containing all the drawings and information we require on site. Pre-planning also includes a review of transport options so that public transport is utilised wherever possible. Route planning and time estimates are considered and a site risk assessment is completed for record.

Photography

Equipment available:

Canon 5D MkIII full frame digital SLR camera (Full frame sensor)

Canon EF 50mm f/1.4 STM lens

Sigma 50mm f/1.4 EX DG HSM

Canon EF 28mm f/1.8 USM Lens

Canon TS-E 24mm f/3.5 L II

Manfrotto Tripod 190

Nodal Ninja Ultimate M2 Panorama Head with Advanced Rotator RD16-II

NN4-D16-Nodal Ninia NN4 Panorama head with RD-16 rotator base

Arca-Swiss Style Standard Camera Plate

NN-EZ-Nodal Ninja EZ Leveler MKII (Tribrach)

Hand held spirit level

Canon RS-80N3 Remote Switch

UV, Polarising, Graduation & neutral density filters

Batteries & chargers

SD card

Plumb bob, tape measure, spray paint & Hilti nails

Compass

Suitable weather conditions are sought so that the proposals may be clearly visible in the context of the view. We endeavor to take the photographs at an appropriate time of day to reduce the chance of the site being in shadow or back-lit. Therefore, when planning a site visit, detailed consideration is given to weather forecasts and sunrise/set times, particularly during the winter when the low angle of the sun can be problematic. The photograph(s) correctly portray the view which is obtained at each representative viewpoint whilst avoiding obvious obstructions.

At each viewpoint the camera is mounted on a tripod at a height of 1.65m above existing ground level, which best represents the average human eye level. The height of the lens "nodal point" is checked by using a tape

The Tribrach and hand held spirit level is used to ensure that the camera is horizontal/vertical. The cameras on board spirit level may also be used. Using the plumb bob, where possible, the "nodal point" is positioned over a pre-surveyed feature which can be identified on the 3D model. Where a pre-existing surveyed feature is not available, spray paint or Hilti nails are used to locate the point for future surveying if required.

As part of the verification procedure, photographs of the tripod and survey point, in situ, are taken using a second camera, so that the surveyor can identify the location. These images are also reproduced in the document to aid on site assessment by third parties if required.

All baseline photographs are taken using the manual settings with a target ISO of 100. A medium aperture with a minimum shutter speed of 1/125 sec ensures that all images are sharp and have a good depth of field. Evaluative metering mode and Auto White Balance is all selected as standard. It should be noted that these settings are preferred but may need to be adjusted according to the climatic or physical conditions.

Photographs are taken in a RAW format using manual settings to enable the best quality results. If necessary, the original RAW file can be submitted as part of the verification process

The photographer takes note of the weather conditions and direction of view. All other details relating to the photograph are stored in the image EXIF data.

Lenses

No 'one size fits all', and we will use the most appropriate set of lenses / formats to convey the view. Only prime lenses are used; in the following order of preference: 50mm, 28mm, 24mm, 24mm/Shift. Both landscape and portrait orientations are considered when planning the photography. The 50mm lens has always been regarded as the "standard" lens on a full frame 35mm camera and closest to the human eye when image printed at A3 and viewed at arm's length. 50mm lenses are not always appropriate for all situations and so when viewing Verified Views based on other lenses, the observer must be aware of the limitations of the printed format. Alternative lenses are only selected when the viewpoint is close to the site. This means that even at a reduced printed scale, the observer is still able to identify all the features visible by the naked eye. (Ref: LI TGN 06/19 Appendix 1.1 & 13.1)

Full Frame Sensor lenses are quoted as having the following Horizontal Fields of View. Canon EF 50mm: 39.6 Degrees / Canon EF 28mm: 65.5 Degrees / Canon TS-E 24mm: 74 Degrees. However, the exact field of view cannot be assumed, and the actual field of view may vary +/- 2 or 3 degrees depending on the lens.

The Effective Focal Lengths (EFL) shown below represent the calculated field of view for our lenses based on known measurements.

Canon EF 50mm f/1.4 STM lens – EFL51.4mm (38.6° HFoV / 26.3° VFoV) Sigma 50mm f/1.4 EX DG HSM – EFL 47.8mm (41.2° HFoV / 28.2° VFoV) Canon EF 28mm f/1.8 USM Lens – EFL 28.2mm (65.1° HFoV / 46.1° VFoV)

Canon TS-E 24mm f/3.5 L II - EFL 24.7mm (73.7° HFoV / 51.8° VFoV)

Image composition and Presentation

Each viewpoint is intended to capture the view as perceived and experienced by the observer.

A practical and aesthetic approach is applied to our viewpoint photography where good composition is important. No one format or lens is suitable for all situations; as a rule of thumb, rural and coastal sites tend to require a 50mm based "panoramic" format (in line with SNH & LI TGN 06/19 guidelines), whilst urban sites can require a more considered approach where alternative lenses and formats may be required.

Viewpoint photographs are taken so that the camera is level to the horizon, so that converging verticals and perspective distortion is avoided. Proposals are in the central portion of the view.

The final baseline viewpoint photographs are single frame planar or composite panoramic images.

Planar or Cylindrical Most technical guidance advises that the final verified views should be presented in Planar format. Therefore, cylindrical "panoramic" views will be re-projected back to planar (53.5° or 60° HFoV) for presentation. Occasionally linear sites or panoramic urban views (such as city scapes, power lines, roads and solar farms for example), may be best presented cylindrically.





5.15 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

When a proposed development is at distance, whilst the observer is aware of the wider area within their peripheral vision they tend to focus on the area in question. In these circumstances it is important to consider the limitations of printed technology and electronic viewing methods and the verified view may presented on a baseline photograph with a smaller field to be reproduced at a scale suitable for viewing at a comfortable arm's length (This can be up to 75mm EFL in accordance with SNH & or 150% according to LI TGN 06/19 guidance). To ensure that the viewer is provided with a representation of the wider context, a "representative" view with a wider horizontal field of view may be presented alongside. This may be a single frame photograph or panorama of either 60° or 90° HFoV and "provides landscape and visual context only"

Most imagery is viewed electronically on screen or printed at A3 with the occasional use of A1 wide by A4 high (840 x 297mm) for panoramic views. Therefore, a sensible balance must be struck to place the proposal within meaningful context whilst providing clarity for the viewer.

See Appendix A for project specific exceptions which may apply to any of the above

Baseline Imagery Processing

Following review in Adobe Bridge, the original Canon RAW files are selected and processed in Adobe Photoshop to adjust white balance, colour accuracy and sharpness. The images undergo further correction procedures to ensure the horizon is precisely horizontal and any lens/barrel distortion is compensated for. The images are then saved as uncompressed Photoshop files for future compositing. Separate .jpg images are saved for use in the camera matching process.

Surveying

The level of accuracy necessary for the individual viewpoints or project as a whole is agreed in advance by the client and planning authority. There are 3 main options;

Option 1: Surveyed Camera Data (±0.1m accuracy)

For each agreed photo viewpoint, a location plan is provided to the surveyor along with marked up referenced photographs showing the camera in situ and the preferred survey reference points. The surveyor then establishes the location of each viewpoint using a Leica Global Positioning System (GPS). Where GPS positioning was not possible near to the required survey point, the surveyor works back from an established GPS location

The surveyor records a range of reference points, using a reflector-less Total Station. Viewpoint marker points are in the foreground and background, high level and low level. These can include existing building ridges, lighting columns, bollards or similar such details. The reference points are individually numbered and referenced on screen-shots or marked up photographs. All reference points must be within the central zone of the photograph where least distortion

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770) Data is presented in Spreadsheet form 3d .dwg plus a photograph marked with the reference points.

Option 2: Using Existing Topographic Survey Data (± 0.1m accuracy)

Where the camera has been taken on or at pre-existing surveyed point, this and the rest of the survey can be used to identify features in the viewpoint. In many cases these include street furniture, manholes, kerbs, buildings, ridge and eave levels or similar. Data is usually provided in a geo-referenced 3d .dwg format, or converted to a 3d format based

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770)

Option 3: Using Publicly available Geographic data (±1.5m accuracy)

Digital Surface Models (DSM) / Digital Terrain Models (DTM) / Ordnance Survey / City (Z) Model / Aerial photography can be used to identify 3D point locations. In many cases these may include existing building ridge-lines & Parapets Street furniture, kerbs or similar such details. Data includes Camera locations and specific 3D points to assist in the camera matching process.

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770)

Note: While in most cases this method will be within the ± 1.5 m accuracy tolerance, depending on the site location and the available data, only ±3-5m accuracy may be achievable in some areas

The proposals supplied by the architects and landscape architects are combined with the site survey and mapping data so that they correspond with each other. A geo-referencing system is used when doing this so that information regarding viewpoints can be accurately located. The model(s) supplied or constructed by us are cross-checked with the site plan and elevations to ensure they accurately match the design drawings, including floor levels, roof heights and footprint.

Camera Matching & Verification:

Irrespective of whether the final VVM is output as a single or composite panoramic image, each Verified View is based upon a single rendered image

Viewpoint markers are used to tie the photograph to the CAD Camera view. These are surveyed features and points such as lamp posts, walls, boundaries and buildings; anything that has a known location. These markers are required to be as accurate as possible and should ideally be positioned within the central portion of the image. They should be at both varying heights, distances and breadth within the view. The background plate photograph is imported into 3ds Max to verify the accuracy of the match.

The location accuracy and angle of view can also be checked by triangulating the position and preparing view line sections. This is a reliable method successfully used for location finding in the field.

There are two ways of camera matching;

For planar baseline photography

This can be achieved within the 3D modeling program by aligning a virtual camera with the reference survey points to obtain an accurate match. The survey is rendered out and, if necessary, this can be adjusted to align correctly to detailed or distant elements that may have been difficult to get pixel perfect precision in 3ds max. The rendered Survey points can then be replaced by the final render to ensure accuracy.

For cylindrical baseline photography:

This can be achieved within the 3D modeling program by aligning virtual planar camera and survey points with a version of the cylindrical image re-projected to a planar perspective. The reference points are then rendered out cylindrically to the required horizontal and vertical FoV, and this is aligned in Photoshop to the cylindrical baseline image. The survey image is then replaced with the rendered model output, based upon the same camera and render

Texturing, Rendering & Post Production

3ds Max is used for applying photo-realistic surfaces and materials to the 3D model. Material references and planting sizes are based upon information provided by the Architects / Landscape Architect

The exact resolution of the photograph is noted and used as the size for the final rendered output of the 3D Model view so that the two overlay each other precisely.

Adobe Photoshop is used to blend the render(s) of the model(s) with the existing baseline / base plate photograph. Where elements are removed from the baseline photograph, reference photography and/ or models of the existing site are used to accurately place elements that were not seen in the original photography

Reproduction

To assist the viewer in understanding the characteristics of the lenses used baseline photographs and verified views can be annotated around the border, to indicate the field of view and optical axis of the lens used This border is divided up into degree increments indicating the field of view. The position of the optical axis indicates whether the photograph was taken with vertical shift. The above added graphic is simply an alternative way of quickly knowing the lens used. This is particularly useful when a number of viewpoints of a proposal are taken with varying lens types.

It is important to reproduce each document and view at the correct size for both practicality and to ensure view accuracy when combined with the listed recommended viewing distance (as detailed on each view)

Each verified view is accompanied by a viewpoint location plan and photographs of camera locations together with the verification data and camera matching reference imagery. A Technical Methodology is included.

The purpose is to reproduce the Verified View so that it correctly reconstructs the perspective seen from the location from which the photograph was taken.

We aim to reproduce all wire frames and photomontages so that they can be viewed at a comfortable arm's length. When comparing the view in the field, the viewer must keep their head motionless and fix their eyes on the centre of the view. This ensures that the represented view falls within the human field of view. If requested an acetate print can be provided for viewing on site. This can help the viewer align the key features on the image with those in real life.

Cylindrical views are only intended for viewing as a printed image or in an appropriate electronic viewing application. The printed image should be viewed on an arc that matches the images field of view, at a

Where it is not possible to represent the proposed site with suitable context in the standard document frame, a larger field of view is necessary. Irrespective of reproduction size all verified views are accurate representation, and the advisory viewing distance (also referred to as Principle Distance by the SNH guidance) is included on all images to allow technical comparison if required.





5.16 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

Appendix A

Appendix A				
Project Title	Proposed Residential Development			
Site Location	Bolton Road, Banbury			
Status	Planning			
Architect	Planning Issues			
Landscape Architect	James Blake Associates			
Coordinate System	OSGB36 (EPSG 277000)			
Accuracy of Viewpoint Location	±0.1m			
Method used to locate camera horizontally	Topographic Survey / Surveyed Camera Position			
Method used to locate camera vertically	Topographic Survey / Surveyed Camera Position			
Camera Matching Technique	Planar (Model Camera Aligned)			
Details used for camera matching - Horizon- tally	Topographic Survey / Surveyed Feature Points			
Details used for camera matching - Vertically	Topographic Survey / Surveyed Feature Points			
Modeling Software	3ds Max / Civil 3d			
Compositing Software	Photoshop / PT GUI			
Other applications	InDesign			
Height and Age of Proposed Planting	Year 5 (7-8m)			
Season(s)	Winter			
LI Visualisation Type	Type 4			
AVR Level	AVR 3			
Design Data Provided	2d CAD Plans			
Photography Equipment Used	Canon 5D full frame digital SLR camera (Full frame sensor) Sigma 50mm f/1.4 EX DG HSM Manfrotto Tripod 190 NNodal Ninja Ultimate M2 Panorama Head with Advanced Rotator RD16-II			

NN-EZ-Nodal Ninja EZ Leveler MKII

Lens and format

50mm

50mm / 100% / 39.6° @ A3

The baseline photograph for Viewpoint 2 was a single photograph taken using the Sigma 50mm f/1.8 lens with a 39.6-degree HFoV, reproduced suitable to be viewed at comfortable arm's length (100% @ A3/A1). This format is selected as suitable to assess a proposed development site which occupies a key portion of the viewpoint requiring a greater level detail to represent in print what may be visible with the naked eye. The verified view can often be presented with an additional viewpoint image with a wider field of view 'for context only'.

50mm / 100% / 53.5° @ A1 Wide

The baseline photographs for Viewpoints 1, 3 & 4 were a composite image taken using the Sigma 50mm f/1.4 lens at intervals of 20 degrees (Landscape Orientation), these images were then stitched together to form a standard 53.5-degree field of view planar image and reproduced suitable to be viewed at comfortable arm's length (100% @ A2 Wide).

Each viewpoint within the document may be supplied with all or some of the following information:

Figure Number	Direction of View (Bearing)	Horizontal Field of View
Viewpoint Number	Camera Height (AGL)	Vertical Field of View
Viewpoint Details	Date & Time	Weather / Lighting Conditions
OS Coordinates (12 digit)	Viewing distance (Advisory)	Camera Type
Eye level (A.O.D)	Single Frame or Composite	Lens / Focal Length



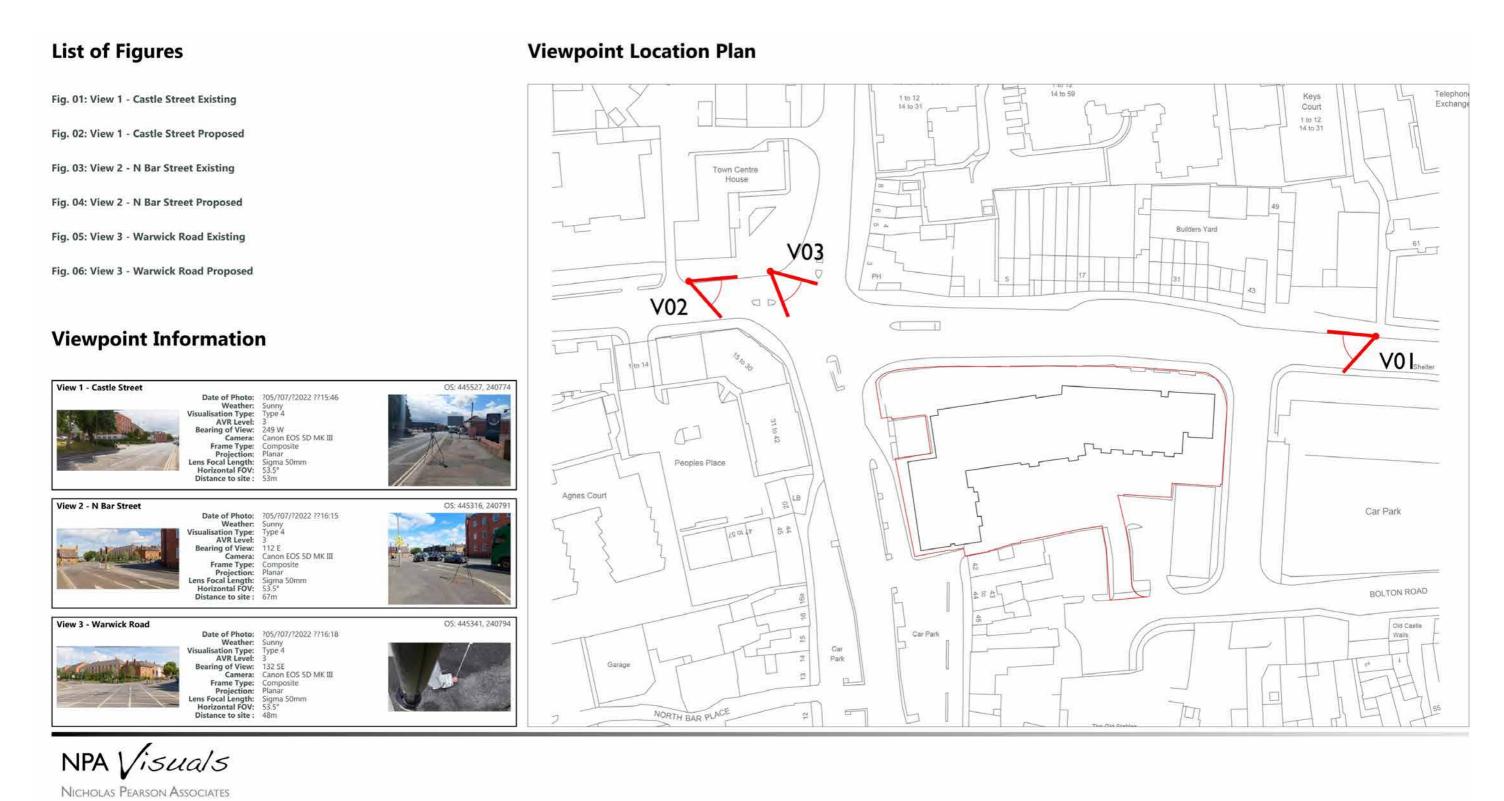


6 Verified Views (Summer)

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6.1 VERIFIED VIEWS - VIEW LOCATIONS





6.2 VERIFIED VIEWS - CASTLE STREET AS EXISTING



NPA Visuals
Nicholas Pearson Associates

Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

 Project No:
 11208-009
 Date:
 February 2022

 Client:
 Churchill Retirement
 Project:
 Bolton Road, Banbury

 Status:
 Planning
 Figure:
 Fig. 01: View 1 - Castle Street Existing

6.3 VERIFIED VIEWS - CASTLE STREET AS EXISTING



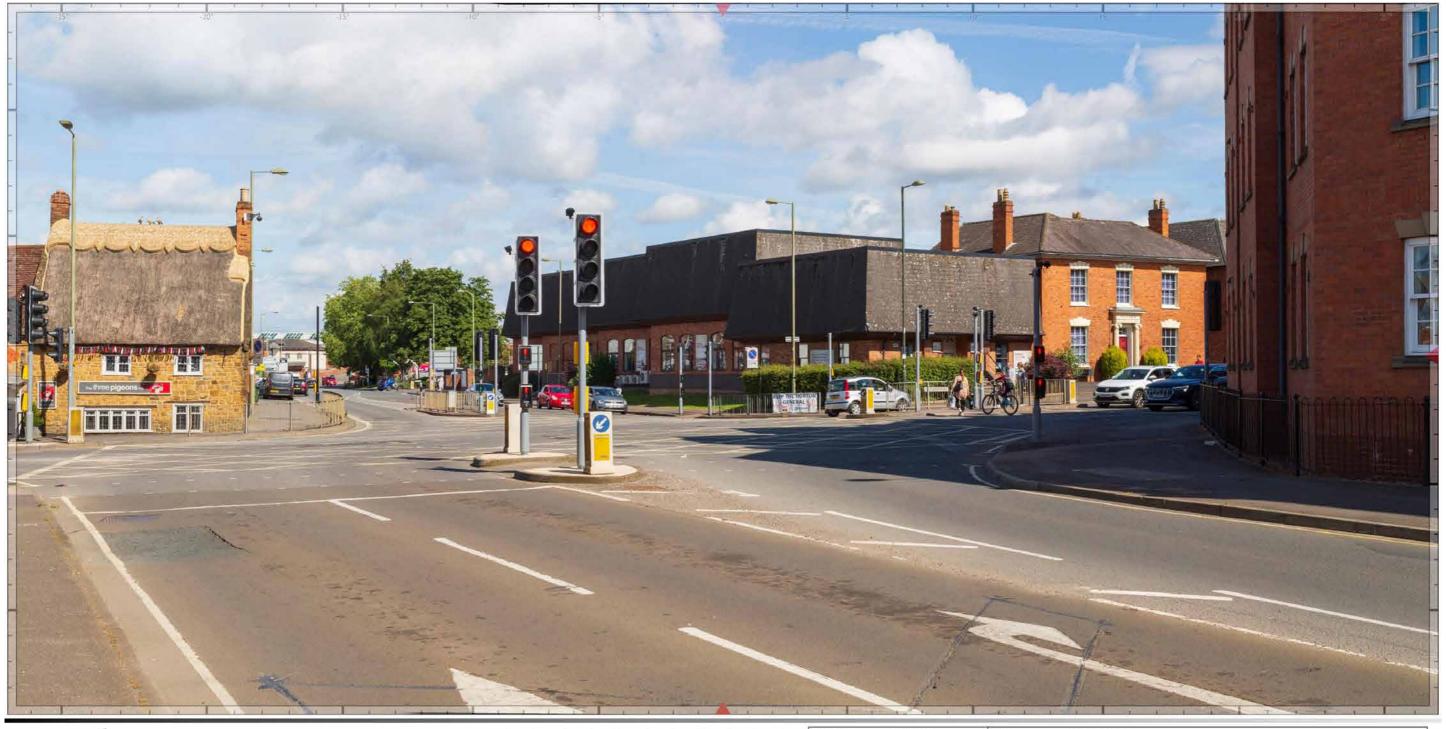
NPA Visuals
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Project No:	11208-009	Date:	February 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 02: View 1 - Castle Street Proposed	

6.4 VERIFIED VIEWS - WARWICK ROAD AS EXISTING



NPA Visuals
Nicholas Pearson Associates

Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No:	11208-009	Date:	February 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 03: View 2 – N Bar Street Existing	

6.5 VERIFIED VIEWS - WARWICK ROAD AS PROPOSED



NPA Visuals
Nicholas Pearson Associates

Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

 Project No:
 11208-009
 Date:
 February 2022

 Client:
 Churchill Retirement
 Project:
 Bolton Road, Banbury

 Status:
 Planning
 Figure:
 Fig. 04: View 2 - N Bar Street Proposed

6.6 VERIFIED VIEWS - CASTLE STREET / NORTH BAR STREET JUNCTION AS EXISTING





Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No: 11208-009 Date: February 2022

Client: Churchill Retirement Project: Bolton Road, Banbury

Status: Planning Figure: Fig. 05: View 3 - Warwick Road Existing

6.7 VERIFIED VIEWS - CASTLE STREET / NORTH BAR STREET JUNCTION AS PROPOSED





Ocm (Original image width 523mm) 10cm

Please note: To view this image digitally, calibrate this scale bar, on screen, for a correct scale representation and view the image at a comfortable arm's length

Project No:	11208-009	Date:	February 2022	
Client:	Churchill Retirement	Project:	Bolton Road, Banbury	
Status:	Planning	Figure:	Fig. 06: View 3 - Warwick Road Proposed	

6.8 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

Introduction

A Verified View is an image that combines a photographic view with an accurate 3d CAD representation of a proposed development, displayed to an agreed level of detail. Using a baseline of verifiable visual data and information, its purpose is to impartially and if required, realistically represent the proposal. Not just the appearance and context, but also its scale. By using verifiable visual data this image can then be used by others (if required) to scrutinise the work, without its accuracy being questioned.

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Photography

Equipment available:

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NN4-D16-Nodal Ninja NN4 Panorama head with RD-16 rotator base

Arca-Swiss Style Standard Camera Plate

NN-EZ-Nodal Ninja EZ Leveler MKII (Tribrach)

Hand held spirit level

Canon RS-80N3 Remote Switch

UV, Polarising, Graduation & neutral density filters

Batteries & chargers

SD cards

Plumb bob, tape measure, spray paint & Hilti nails

Compas

Suitable weather conditions are sought so that the proposals may be clearly visible in the context of the view. We endeavor to take the photographs at an appropriate time of day to reduce the chance of the site being in shadow or back-lit. Therefore, when planning a site visit, detailed consideration is given to weather forecasts and sunrise/set times, particularly during the winter when the low angle of the sun can be problematic. The photograph(s) correctly portray the view which is obtained at each representative viewpoint whilst avoiding obstructions.

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The Tribrach and hand held spirit level is used to ensure that the camera is horizontal/vertical. The cameras on board spirit level may also be used. Using the plumb bob, where possible, the "nodal point" is positioned over a pre-surveyed feature which can be identified on the 3D model. Where a pre-existing surveyed feature is not available, spray paint or Hilti nails are used to locate the point for future surveying if required.

As part of the verification procedure, photographs of the tripod and survey point, in situ, are taken using a second camera, so that the surveyor can identify the location. These images are also reproduced in the document to aid on site assessment by third parties if required.

All baseline photographs are taken using the manual settings with a target ISO of 100. A medium aperture with a minimum shutter speed of 1/125 sec ensures that all images are sharp and have a good depth of field. Evaluative metering mode and Auto White Balance is all selected as standard. It should be noted that these settings are preferred but may need to be adjusted according to the climatic or physical conditions.

Photographs are taken in a RAW format using manual settings to enable the best quality results. If necessary, the original RAW file can be submitted as part of the verification process

The photographer takes note of the weather conditions and direction of view. All other details relating to the photograph are stored in the image EXIF data.

Lenses

No 'one size fits all', and we will use the most appropriate set of lenses / formats to convey the view. Only prime lenses are used; in the following order of preference: 50mm, 28mm, 24mm, 24mm/Shift. Both landscape and portrait orientations are considered when planning the photography. The 50mm lens has always been regarded as the "standard" lens on a full frame 35mm camera and closest to the human eye when image printed at A3 and viewed at arm's length. 50mm lenses are not always appropriate for all situations and so when viewing Verified Views based on other lenses, the observer must be aware of the limitations of the printed format. Alternative lenses are only selected when the viewpoint is close to the site. This means that even at a reduced printed scale, the observer is still able to identify all the features visible by the naked eye. (Ref: LI TGN 06/19 Appendix 1.1 & 13.1)

Full Frame Sensor lenses are quoted as having the following Horizontal Fields of View. Canon EF 50mm: 39.6 Degrees / Canon EF 28mm: 65.5 Degrees / Canon TS-E 24mm: 74 Degrees. However, the exact field of view cannot be assumed, and the actual field of view may vary +/- 2 or 3 degrees depending on the lens.

The Effective Focal Lengths (EFL) shown below represent the calculated field of view for our lenses based on known measurements.

Canon EF 50mm f/1.4 STM lens – EFL51.4mm (38.6° HFoV / 26.3° VFoV) Sigma 50mm f/1.4 EX DG HSM – EFL 47.8mm (41.2° HFoV / 28.2° VFoV) Canon EF 28mm f/1.8 USM Lens – EFL 28.2mm (65.1° HFoV / 46.1° VFoV)

Canon TS-E 24mm f/3.5 L II - EFL 24.7mm (73.7° HFoV / 51.8° VFoV)

Image composition and Presentation

Each viewpoint is intended to capture the view as perceived and experienced by the observer.

A practical and aesthetic approach is applied to our viewpoint photography where good composition is important. No one format or lens is suitable for all situations; as a rule of thumb, rural and coastal sites tend to require a 50mm based "panoramic" format (in line with SNH & LI TGN 06/19 guidelines), whilst urban sites can require a more considered approach where alternative lenses and formats may be required.

Viewpoint photographs are taken so that the camera is level to the horizon, so that converging verticals and perspective distortion is avoided. Proposals are in the central portion of the view.

The final baseline viewpoint photographs are single frame planar or composite panoramic images.

Planar or Cylindrical? Most technical guidance advises that the final verified views should be presented in Planar format. Therefore, cylindrical "panoramic" views will be re-projected back to planar (53.5° or 60° HFoV) for presentation. Occasionally linear sites or panoramic urban views (such as city scapes, power lines, roads and solar farms for example), may be best presented cylindrically.





6.9 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

When a proposed development is at distance, whilst the observer is aware of the wider area within their peripheral vision they tend to focus on the area in question. In these circumstances it is important to consider the limitations of printed technology and electronic viewing methods and the verified view may presented on a baseline photograph with a smaller field to be reproduced at a scale suitable for viewing at a comfortable arm's length (This can be up to 75mm EFL in accordance with SNH & or 150% according to LI TGN 06/19 guidance). To ensure that the viewer is provided with a representation of the wider context, a "representative" view with a wider horizontal field of view may be presented alongside. This may be a single frame photograph or panorama of either 60° or 90° HFOV and "provides landscape and visual context only"

Most imagery is viewed electronically on screen or printed at A3 with the occasional use of A1 wide by A4 high (840 x 297mm) for panoramic views. Therefore, a sensible balance must be struck to place the proposal within meaningful context whilst providing clarity for the viewer.

See Appendix A for project specific exceptions which may apply to any of the above

Baseline Imagery Processing

Following review in Adobe Bridge, the original Canon RAW files are selected and processed in Adobe Photoshop to adjust white balance, colour accuracy and sharpness. The images undergo further correction procedures to ensure the horizon is precisely horizontal and any lens/barrel distortion is compensated for. The images are then saved as uncompressed Photoshop files for future compositing. Separate .jpg images are saved for use in the camera matching process.

Surveying

The level of accuracy necessary for the individual viewpoints or project as a whole is agreed in advance by the client and planning authority. There are 3 main options;

Option 1: Surveyed Camera Data (±0.1m accuracy)

For each agreed photo viewpoint, a location plan is provided to the surveyor along with marked up referenced photographs showing the camera in situ and the preferred survey reference points. The surveyor then establishes the location of each viewpoint using a Leica Global Positioning System (GPS). Where GPS positioning was not possible near to the required survey point, the surveyor works back from an established GPS location.

The surveyor records a range of reference points, using a reflector-less Total Station. Viewpoint marker points are in the foreground and background, high level and low level. These can include existing building ridges, lighting columns, bollards or similar such details. The reference points are individually numbered and referenced on screen-shots or marked up photographs. All reference points must be within the central zone of the photograph where least distortion occurs.

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770)

Data is presented in Spreadsheet form 3d .dwg plus a photograph marked with the reference points.

Option 2: Using Existing Topographic Survey Data (± 0.1m accuracy)

Where the camera has been taken on or at pre-existing surveyed point, this and the rest of the survey can be used to identify features in the viewpoint. In many cases these include street furniture, manholes, kerbs, buildings, ridge and eave levels or similar. Data is usually provided in a geo-referenced 3d .dwg format, or converted to a 3d format based on stated levels in the survey.

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770)

Option 3: Using Publicly available Geographic data (±1.5m accuracy)

Digital Surface Models (DSM) / Digital Terrain Models (DTM) / Ordnance Survey / City (Z) Model / Aerial photography can be used to identify 3D point locations. In many cases these may include existing building ridge-lines & Parapets, Street furniture, kerbs or similar such details. Data includes Camera locations and specific 3D points to assist in the camera matching process.

Data processing is conducted and referenced back to Ordnance Survey Grid (OSGB36 / EPSG 2770)

Note: While in most cases this method will be within the $\pm 1.5m$ accuracy tolerance, depending on the site location and the available data, only $\pm 3.5m$ accuracy may be achievable in some areas

3d Modeling

The proposals supplied by the architects and landscape architects are combined with the site survey and mapping data so that they correspond with each other. A geo-referencing system is used when doing this so that information regarding viewpoints can be accurately located. The model(s) supplied or constructed by us are cross-checked with the site plan and elevations to ensure they accurately match the design drawings, including floor levels, roof heights and footprint.

Camera Matching & Verification

Irrespective of whether the final VVM is output as a single or composite panoramic image, each Verified View is based upon a single rendered image.

Viewpoint markers are used to tie the photograph to the CAD Camera view. These are surveyed features and points such as lamp posts, walls, boundaries and buildings; anything that has a known location. These markers are required to be as accurate as possible and should ideally be positioned within the central portion of the image. They should be at both varying heights, distances and breadth within the view. The background plate photograph is imported into 3ds Max to verify the accuracy of the match.

The location accuracy and angle of view can also be checked by triangulating the position and preparing view line sections. This is a reliable method successfully used for location finding in the field.

There are two ways of camera matching;

For planar baseline photography:

This can be achieved within the 3D modeling program by aligning a virtual camera with the reference survey points to obtain an accurate match. The survey is rendered out and, if necessary, this can be adjusted to align correctly to detailed or distant elements that may have been difficult to get pixel perfect precision in 3ds max. The rendered Survey points can then be replaced by the final render to ensure accuracy.

For cylindrical baseline photography:

This can be achieved within the 3D modeling program by aligning virtual planar camera and survey points with a version of the cylindrical image re-projected to a planar perspective. The reference points are then rendered out cylindrically to the required horizontal and vertical FoV, and this is aligned in Photoshop to the cylindrical baseline image. The survey image is then replaced with the rendered model output, based upon the same camera and render settings.

Texturing, Rendering & Post Production

3ds Max is used for applying photo-realistic surfaces and materials to the 3D model. Material references and planting sizes are based upon information provided by the Architects / Landscape Architect

The exact resolution of the photograph is noted and used as the size for the final rendered output of the 3D Model view so that the two overlay each other precisely.

Adobe Photoshop is used to blend the render(s) of the model(s) with the existing baseline / base plate photograph. Where elements are removed from the baseline photograph, reference photography and/or models of the existing site are used to accurately place elements that were not seen in the original photography

Reproduction

To assist the viewer in understanding the characteristics of the lenses used baseline photographs and verified views can be annotated around the border, to indicate the field of view and optical axis of the lens used. This border is divided up into degree increments indicating the field of view. The position of the optical axis indicates whether the photograph was taken with vertical shift. The above added graphic is simply an alternative way of quickly knowing the lens used. This is particularly useful when a number of viewpoints of a proposal are taken with varying lens types.

It is important to reproduce each document and view at the correct size for both practicality and to ensure view accuracy when combined with the listed recommended viewing distance (as detailed on each view)

Each verified view is accompanied by a viewpoint location plan and photographs of camera locations together with the verification data and camera matching reference imagery. A Technical Methodology is included.

Viewing Procedures

The purpose is to reproduce the Verified View so that it correctly reconstructs the perspective seen from the location from which the photograph was taken.

We aim to reproduce all wire frames and photomontages so that they can be viewed at a comfortable arm's length. When comparing the view in the field, the viewer must keep their head motionless and fix their eyes on the centre of the view. This ensures that the represented view falls within the human field of view. If requested an acetate print can be provided for viewing on site. This can help the viewer align the key features on the image with those in real life.

Cylindrical views are only intended for viewing as a printed image or in an appropriate electronic viewing application. The printed image should be viewed on an arc that matches the images field of view, at a comfortable arms-length.

Where it is not possible to represent the proposed site with suitable context in the standard document frame, a larger field of view is necessary. Irrespective of reproduction size all verified views are accurate representation, and the advisory viewing distance (also referred to as Principle Distance by the SNH guidance) is included on all images to allow technical comparison if required.





6.10 VERIFIED VIEWS - VIEW METHODOLOGY

Visually Verifiable Montage Methodology

Appendix A

Project Title	Proposed Residential Development		
Site Location	Bolton Road, Banbury		
Status	Planning		
Architect	Planning Issues		
Landscape Architect	James Blake Associates		
Coordinate System	OSGB36 (EPSG 277000)		
Accuracy of Viewpoint Location	±0.1m		
Method used to locate camera horizontally	Topographic Survey / Surveyed Camera Position		
Method used to locate camera vertically	Topographic Survey / Surveyed Camera Position		
Camera Matching Technique	Planar (Model Camera Aligned)		
Details used for camera matching - Horizon- tally	Topographic Survey / Surveyed Feature Points		
Details used for camera matching - Vertically	Topographic Survey / Surveyed Feature Points		
Modeling Software	3ds Max		
Compositing Software	Photoshop / PT GUI		
Other applications	InDesign		
Height and Age of Proposed Planting	Year 5 (7-8m)		
Season(s)	Summer		
LI Visualisation Type	Type 4		
AVR Level	AVR 3		
Design Data Provided	2d CAD Plans		
Photography Equipment Used	Canon 5D full frame digital SLR camera (Full frame sensor) Sigma 50mm f/1.4 EX DG HSM Manfrotto Tripod 190 NNodal Ninja Ultimate M2 Panorama Head with Advanced Rotator RD16-II NN-EZ-Nodal Ninja EZ Leveler MKII		

Lens and format

50mm

50mm / 100% / 53.5° @ A1 Wide

The baseline photographs for the Viewpoints were a composite image taken using the Sigma 50mm f/1.4 lens at intervals of 20 degrees (Landscape Orientation), these images were then stitched together to form a standard 53.5-degree field of view planar image and reproduced suitable to be viewed at comfortable arm's length (100% @ A1wide). This format is selected as suitable for assessing sites which sit within a panoramic landscape setting and derives from the SNH Visual representation of wind farms.

Additional Comments

(regarding proportionality etc. - for example was a certain AVR level chosen due to project scope.)

Each viewpoint within the document may be supplied with all or some of the following information:

Figure Number Direction of View (Bearing) Horizontal Field of View Viewpoint Number Camera Height (AGL) Vertical Field of View Viewpoint Details Date & Time Weather / Lighting Conditions OS Coordinates (12 digit) Viewing distance (Advisory) Camera Type Single Frame or Composite Eye level (A.O.D) Lens / Focal Length

Model and camera location accuracy

The Verified views in this document may also contain other information such as:

Illustrative bar indicating compass bearing

Extent of central 50mm frame used to construct panorama Extent of which Proposed development occupy - (Degrees Number of buildings visible

Note on A3 versions: "This image provides landscape and visual context only."

Annotation of key features Note: "View flat at a comfortable Building ID numbers

Viewpoint Pack: Note: This image is intended only for use at the viewpoint.

Wirelines views are colour coded as follows:

DTM - Grey/Black Waterbodies - Light Blue Proposed structures - Brown Existing structures - Blue Proposed Vegetation - Light Green Existing Vegetation - Dark Green





7 Revised Plans and Elevations

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7.1 SITE PLAN

PA01 Site Plan, revision C





7.2 GROUND FLOOR PLAN

PA02 Ground Floor Plan, revision B Trelawn House Ground Floor Plan Churchill
Retirement Living



10116BB - PA02 B

7.3 FIRST FLOOR PLAN

PA03 First Floor Plan, revision A Trelawn DENOTES LOCATION OF MODIFICACI First Floor Plan Churchill Retirement Living



10116BB - PA03 A

7.4 SECOND FLOOR PLAN

PA04 Second Floor Plan, revision A Trelawn Second Floor Plan Churchill Retirement Living



10116BB - PA04 A

7.5 THIRD FLOOR PLAN

PA05 Third Floor Plan, revision A Trelawn DENOTES LOCATION OF BOOTLIGHT Third Floor Plan Churchill
Retirement Living



10116BB - PA05 A

7.6 ROOF PLAN

PA06 Roof Plan, revision A Trelawn House DENOTES LOCATION OF MICORLIGHT Planning issues
Rob Jackson RIBA Roof Plan Churchill Retirement Living



10116BB - PA06 A

7.7 CASTLE STREET ELEVATION

PA07 Castle Street Elevation, revision B



7.8 NORTH BAR STREET ELEVATION

PA08 North Bar Street Elevation, revision B



7 APPEAL PLANS AND ELEVATIONS

7.9 INTERNAL AND OTHER ELEVATIONS

PA09 Other Elevations, revision B





8 CONSERVATION AREA AND LISTED BUILDING PLAN

8 Conservation Area

8.1 Conservation Area & Listed Building Plan

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8 CONSERVATION AREA AND LISTED BUILDING PLAN

8.1 CONSERVATION AREA AND LISTED BUILDING PLAN

Image from ECUS Heritage Statement

